

## **ECE 6342 Fall 2016 HW 4 Thurs Due 9/22**

Problems from Discrete-time Signal Processing - Oppenheim , 2nd edition Chapter 3

**Problem 1.** Oppenheim 3.55 (a) only

**Problem 2.** Oppenheim 4.3

**Problem 3.** Oppenheim 4.5

**Problem 4.** Oppenheim 4.6

**Problem 5.** Oppenheim 4.12

**Problem 6.** Oppenheim 4.15

**3.55.** The aperiodic autocorrelation function for a real-valued stable sequence  $x[n]$  is defined as

$$c_{xx}[n] = \sum_{k=-\infty}^{\infty} x[k]x[n+k].$$

(a) Show that the  $z$ -transform of  $c_{xx}[n]$  is

$$C_{xx}(z) = X(z)X(z^{-1}).$$

Determine the region of convergence for  $C_{xx}(z)$ .

**4.3.** The continuous-time signal

$$x_c(t) = \cos(4000\pi t)$$

is sampled with a sampling period  $T$  to obtain a discrete-time signal

$$x[n] = \cos\left(\frac{\pi n}{3}\right).$$

(a) Determine a choice for  $T$  consistent with this information.

(b) Is your choice for  $T$  in Part (a) unique? If so, explain why. If not, specify another choice of  $T$  consistent with the information given.

**4.5.** Consider the system of Figure 4.11, with the discrete-time system an ideal lowpass filter with cutoff frequency  $\pi/8$  radians/s.

(a) If  $x_c(t)$  is bandlimited to 5 kHz, what is the maximum value of  $T$  that will avoid aliasing in the C/D converter?

(b) If  $1/T = 10$  kHz, what will the cutoff frequency of the effective continuous-time filter be?

(c) Repeat Part (b) for  $1/T = 20$  kHz.

**4.6.** Let  $h_c(t)$  denote the impulse response of a linear time-invariant continuous-time filter and  $h_d[n]$  the impulse response of a linear time-invariant discrete-time filter.

(a) If

$$h_c(t) = \begin{cases} e^{-at}, & t \geq 0, \\ 0, & t < 0, \end{cases}$$

where  $a$  is a positive real constant, determine the continuous-time filter frequency response and sketch its magnitude.

(b) If  $h_d[n] = Th_c(nT)$  with  $h_c(t)$  as in part (a), determine the discrete-time filter frequency response and sketch its magnitude.

(c) For a given value of  $a$ , determine, as a function of  $T$ , the minimum magnitude of the discrete-time filter frequency response.

**4.12.** In the system of Figure 4.11, assume that

$$H(e^{j\omega}) = j\omega/T, \quad -\pi \leq \omega < \pi,$$

and  $T = 1/10$  sec.

**(a)** For each of the following inputs  $x_c(t)$ , find the corresponding output  $y_c(t)$ .

(i)  $x_c(t) = \cos(6\pi t)$

(ii)  $x_c(t) = \cos(14\pi t)$

**(b)** Are the outputs  $y_c(t)$  those you would expect from a differentiator?

**4.15.** Consider the system shown in Figure P4.15-1. For each of the following input signals  $x[n]$ , indicate whether the output  $x_r[n] = x[n]$ .

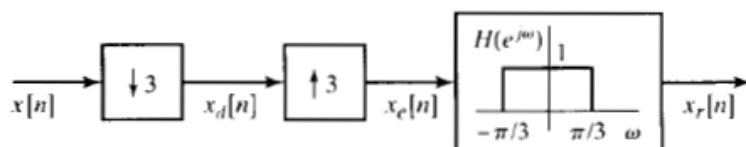
**(a)**  $x[n] = \cos(\pi n/4)$

**(b)**  $x[n] = \cos(\pi n/2)$

**(c)**

$$x[n] = \left[ \frac{\sin(\pi n/8)}{\pi n} \right]^2$$

*Hint:* Use the modulation property of the Fourier transform to find  $X(e^{j\omega})$ .



**Figure P4.15-1**