

Midterm Exam II - October 29, 2018

Each sub-question in the following carries equal weight except when otherwise noted.

1. (20%)
 - a) Explain what a duration model is, including the definition of the survivor function and the hazard function.
 - b) Derive the hazard function for the exponential duration model.
 - c) Write down the likelihood function for a sample of observations from an exponential duration model with some incomplete spells.
2. (18%)
 - a) Find the estimated β that minimizes $(Y - X\beta)'W(Y - X\beta)$, where Y is a $T \times 1$ vector, X a $T \times k$ vector, and W is a full rank symmetric “weighting matrix.”
 - b) Assuming that $Y - X\beta$ has variance matrix Ω , derive the variance of the estimated β
3. (16%) In the weak-IV survey article by Murray, there is a formula that I asked you memorize. In that formula, there are 4 factors that determines the approximate bias. of 2SLS. What are these factors (4% for each).
4. (16%)
 - a) In the following code, what is the object B_{xxx} calculated where there is an A:?
 - b) In the following code, what is the object B_{yyy} calculated where there is an B:?
 - c) Explain why you might want to use B_{yyy} or B_{xxx} under certain conditions (which?).

```
X = [ones(T,1) x1 x2 x3 x4 x5 x6 x7 x8 x9 x10 x11 x12 x13];           %exogenous
for s = 1:sim

    u1 = normrnd(0,sigma1,T,1);                                       % Residuals for equ
    u2 = normrnd(0,sigma2,T,1) + 5*u1;                               % Residuals for equ

    y2 = beta3 + beta4*x1 + beta5*x2 + beta6*x3 + beta7*x4 + beta8*x5 + beta9*x6 + beta10*x7 +
    y1 = beta0 + beta1*y2 + beta2*x1 + u1;

    Y = [y1 y2];
    Y1 = Y(:,1); %same as y1
```

```

Y2 = Y(:,2); %endogenous regressors, same as generated y2

X_exo1 = X(:,1:2); %exogenous regressors in the reduced form
X_OLS=[ones(T,1) Y2 x1];

    B2_hat = inv(X'*X)*X'*Y2;
    Y2_hat = X*B2_hat;
    X1_hat = [ones(T,1) Y2_hat x1];
A:    B_xxx(s,:) = inv(X1_hat'*X1_hat)*X1_hat'*Y1;

N = length(Y2);
Mexo = eye(N) - X*inv(X'*X)*X'; %projection matrix, X is
Mexo1 = eye(N) - X_exo1*inv(X_exo1'*X_exo1)*X_exo1';
W = [Y1 Y2]'*(Mexo)*[Y1 Y2]; %2x2 matrix
W1 = [Y1 Y2]'*(Mexo1)*[Y1 Y2]; %2x2 matrix
lambda = min( eig(inv(W)*W1 ) );
B:    B_yyy(s,:) = inv(X_OLS'*(eye(N)-(lambda*Mexo))*X_OLS)*(X_OLS'*(eye(N)-(lambda*Mexo))*Y1)

```

5. (30%) Consider a GMM problem where you have a sample of scalar observations y_t , ($t = 1, \dots, T$), which satisfies $E y_t = h(x_t; \theta)$, where x_t is vector of observed variables and θ a K -dimensional vector of unknown parameters that you want to estimate. You further have access (for each t) to an L -dimensional vector z_t which satisfies $L > K$ and $E\{z_t*(y_t - h(x_t; \theta))\} = 0$ for a unique value θ_0 .

- Write down the formula for GMM estimator (with identity weighting matrix) of θ in terms of the variables given.
- Using the notation of my notes., identify where f_t is calculated in the text (e.g., what is the name used in the code?), where g_T is calculated and where the criterion function is calculated.
- Explain in words how the test for overidentifying restrictions is calculated and what is its distribution?

GMM CODE.

```
%{
```

```

Xavier Martin G. Bautista
Fall 2018
Macro 3
HW 2

```

```
GMM_Main.m
```

This replicates Hansen and Singleton (1982). Estimation is done using GMM. The variance matrix can be estimated using either Newey-West or Quadratic Spectral kernels.

Note: Convention used is $U(C) = (C^{(1-\gamma)})/(1-\gamma)$.

%}

%% 1. Change working directory and load data.

```
close all
clear
clc
```

```
addpath('D:/Xavier_Laptops/Xavier_Asus/Xavier_Classes/Fall_2018/Macro3/HW2')
```

```
global c lag re rf n T Z
```

```
load data
```

```
lag = 3; % Number of lags used
```

```
c = data(:,1); % c(t)/c(t-1).
```

```
re = data(:,2); % Value-weighted average return
```

```
rf = data(:,3); % T-bill rate.
```

```
T = size(data,1);
```

```
Z = [ones(T-lag,1) c(1:T-3) c(2:T-2) c(3:T-1)... % Instruments: 3 lags
```

```
re(1:T-3) re(2:T-2) re(3:T-1)... % value-weighted average return
```

```
rf(1:T-3) rf(2:T-2) rf(3:T-1)];
```

```
n = size(Z,2); % Number of instruments
```

```
clear data
```

%% 2. GMM Stage 1: Identity Weighting Matrix.

```
b0 = [0.5 0.5]; % Initial guess of parameter vector
```

```
W = weight(b0,0); % W = Identity matrix
```

```
opt = optimset('FinDiffType','central','HessUpdate','BFGS'); % Use central diff
```

```

b1 = fminunc('gmm_obj',b0,opt,W);
clear W

*****
function crit = gmm_xxx(guess,W)

global lag T

mom = ((sum(orth(guess),1))./(T-lag))';
crit = mom'*W*mom;

end
*****
function ZXb = orth(guess)

%{
    orth.m

    This is the orthogonality condition from Hansen and Singleton (1982)
     $E(z(t) * ((\beta * (C(t)/C(t-1))^{-\gamma}) * r(t)) - 1) = 0.$ 
%}

global c lag n rf T Z

beta = guess(1);
gamma = guess(2);

C = repmat(c(1+lag:T),1,n);
R = repmat(rf(1+lag:T),1,n);

ZXb = Z.*((beta.*(C.^(-gamma)).*R)-1);

end
*****

```