

Midterm Exam - October 1, 2018

Each sub-question in the following carries equal weight except when otherwise noted.

1. (26%)

Assume that you have data for consumption c_i and income y_i for a sample $i = 1, \dots, N$ and that you want to estimate the relation

$$c_i = \alpha + \beta y_i + \epsilon_i ,$$

where ϵ_i is normally distributed with mean 0 and variance σ^2 .

- a) (3%) If observations with $c_i > 100$ were excluded from the sample, what is this pattern labeled?
- b) (10%) And what would be the log likelihood function? (Write it out explicitly.)
- c) (3%) If instead observations $c_i > 100$ were replaced with $c_i = 100$, what is the term (label) for the model that takes this into account?
- d) (10%) What would be the log likelihood function? (Write it out explicitly.)

2. (24%) On the next pages, I have reproduced a piece of Matlab code that you used for a homework.

- a) 8%) Explain what the code is supposed to do.
- b) 8%) Explain what the two lines for `z(i)==1` are capturing?
- c) 8%) Explain intuitively what happens if `rho==0`.

3) 25%) Consider the stationary AR(2) model

$$x_t = ax_{t-1} + bx_{t-2} + u_t ,$$

where u_t is normally distributed with variance σ^2 . Assume the variance-covariance matrix for x_t, x_{t-1} , and x_{t-2} is

$$\Sigma_x = \begin{pmatrix} \gamma_0 & \gamma_1 & \gamma_2 \\ \gamma_1 & \gamma_0 & \gamma_1 \\ \gamma_2 & \gamma_1 & \gamma_0 \end{pmatrix} .$$

Assume you have a sample of observations $x_t, t = 1, \dots, T$. Write down the first three terms of

the unconditional likelihood function; i.e., $f(x_1)$, $f(x_2|x_1)$, and $f(x_3|x_1, x_2)$. (You can write the *log*-likelihood, if you want, the main point is the unconditional and conditional distributions appearing in these three terms. Do not try to invert any matrices, I need to see that you know/can derive the formulas.)

4) (25%)

Prove that, in a system of equations (think of 2 equations and a sample of years for simplicity), where the two error terms are correlated, if the right hand side regressors are the same for each dependent variable, you can estimate the equations one-by-one and obtain the same estimator as if you used GLS on the full system. (Assume that observations are independent across years.)

Code

```
function [L] = logl_ss(b)

global x w y z N

b0 = b(1);
b1 = b(2);
sigmau = b(3);
g0 = b(4);
g1 = b(5);
rho = b(6);

XB = b0*ones(size(x,1),1) + b1*x ;
WG = g0*ones(size(w,1),1) + g1*w ;

L=0 ;

for i = 1:N
    if z(i) == 1
        L = L + log((1/sigmau)*normpdf((y(i) - XB(i))/sigmau))...
            + log(normcdf((1/sqrt(abs(1-rho^2)))*(WG(i) + (rho/sigmau)*(y(i) - XB(i))))));
    elseif z(i) == 0
        L = L + log(normcdf(-WG(i)));
    end
end

L = -L;

end
```